

L Number	Hits	Search Text	DB	Time stamp
1	21	((vehicle or tractor or agricultur\$4)and ((parallel same line same path)or(concentric same polygon same path))and (base near4 station)and (position\$4 same correct\$4)and (path same offset)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/12 13:56
2	22	((vehicle or tractor or agricultur\$4)and ((parallel same line same path)or(concentric same polygon same path))and (base same station)and (position\$4 same correct\$4)and (path same offset)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/12 13:58
3	127	(GPS same receiver)and accelerometer and (inertial same relative same position\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/12 13:58
4	0	((vehicle or tractor or agricultur\$4)and ((parallel same line same path)or(concentric same polygon same path))and (base same station)and (position\$4 same correct\$4)and (path same offset) ) and ((GPS same receiver)and accelerometer and (inertial same relative same position\$4))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/12 13:57
5	211	((vehicle or tractor or agricultur\$4)and ((parallel same line same path)or(concentric same polygon same path))and (base same station))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/12 13:59
6	0	((GPS same receiver)and accelerometer and (inertial same relative same position\$4)) and ((vehicle or tractor or agricultur\$4)and ((parallel same line same path)or(concentric same polygon same path))and (base same station))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/12 13:58
7	336	(GPS same receiver)and accelerometer and (inertial same position\$4)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/12 13:58
8	0	((vehicle or tractor or agricultur\$4)and ((parallel same line same path)or(concentric same polygon same path))and (base same station)) and ((GPS same receiver)and accelerometer and (inertial same position\$4))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/12 13:58
9	455	(GPS )and receiver and accelerometer and (inertial )	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/12 14:00
10	336	((GPS same receiver)and accelerometer and (inertial same position\$4)) and ((GPS )and receiver and accelerometer and (inertial ))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/12 13:59
11	0	((vehicle or tractor or agricultur\$4)and ((parallel same line same path)or(concentric same polygon same path))and (base same station)) and ((GPS )and receiver and accelerometer and (inertial ))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/12 13:59
12	367	((vehicle or tractor or agricultur\$4)and ((parallel same line same path)or(concentric same polygon same path))and (path same offset))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/12 14:05
13	0	((GPS )and receiver and accelerometer and (inertial )) and ((vehicle or tractor or agricultur\$4)and ((parallel same line same path)or(concentric same polygon same path))and (path same offset))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/12 13:59



14	1328	((vehicle or tractor or aggricultur\$4)and ((parallel same path)or(concentric same polygon same path))and (path same offset)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/12 14:24
15	595	(GPS ) and accelerometer and (inertial )	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/12 14:00
16	20	((vehicle or tractor or aggricultur\$4)and ((parallel same path)or(concentric same polygon same path))and (path same offset)) and ((GPS ) and accelerometer and (inertial ))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/12 14:00
17	31	((vehicle or tractor or aggricultur\$4)and ((parallel same path)or(concentric same polygon same path))and (path same offset)and accelerometer	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/12 14:05
18	21	((vehicle or tractor or aggricultur\$4)and ((parallel same path)or(concentric same polygon same path))and (path same offset)and accelerometer and speed and inertial	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/12 14:07
19	24	((vehicle or tractor or aggricultur\$4)and ((parallel same path)or(concentric same polygon same path))and (path same offset)and accelerometer and (relative near4 position)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/12 14:08
27	1328	((vehicle or tractor or aggricultur\$4)and (parallel same path)and (path same offset)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/12 14:24
28	25	((vehicle or tractor or aggricultur\$4)and (parallel same path)and (path same offset)and receiver and accelerometer	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/12 14:38
29	28	((vehicle or tractor or aggricultur\$4)and (parallel same path)and (path same offset)and (relative same position) and accelerometer	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/12 14:26
30	24	((vehicle or tractor or aggricultur\$4)and (parallel same path)and (path same offset)and (relative near4 position) and accelerometer	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/12 14:27
31	91	((vehicle or tractor or aggricultur\$4)and (parallel near4 path)and (path near4 offset)and (relative near4 position)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/12 14:27
32	25	((vehicle or tractor or aggricultur\$4)and (parallel near4 path)and (path same offset)and receiver and accelerometer	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/12 14:38
33	19	((vehicle or tractor or aggricultur\$4)and (parallel near4 path)and (path near4 offset)and receiver and accelerometer and speed and inertial	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/12 14:41
34	70839	(parallel near4 path)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/02/12 14:41
35	1	5956250.pn.	USPAT	2004/02/12 14:41
36	1	(( parallel near4 path)) and 5956250.pn.	USPAT	2004/02/12 14:41